

« EMR-based control of a particle injector »

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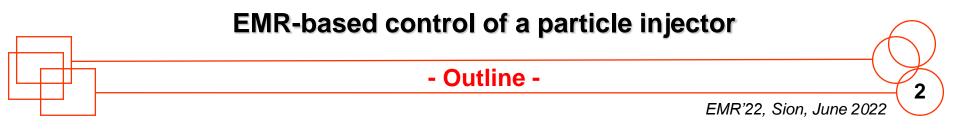
University of Lille, France

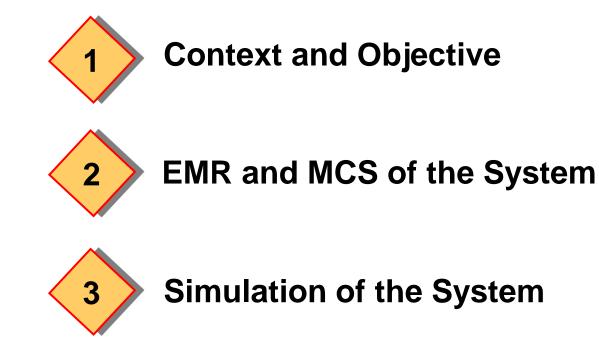


Université de Lille

In collaboration with:

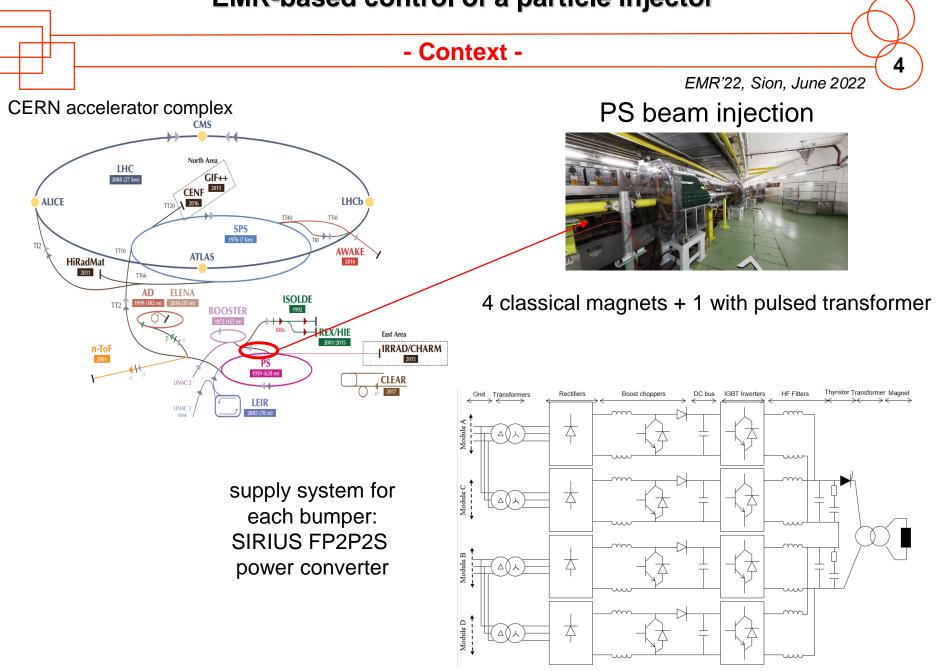




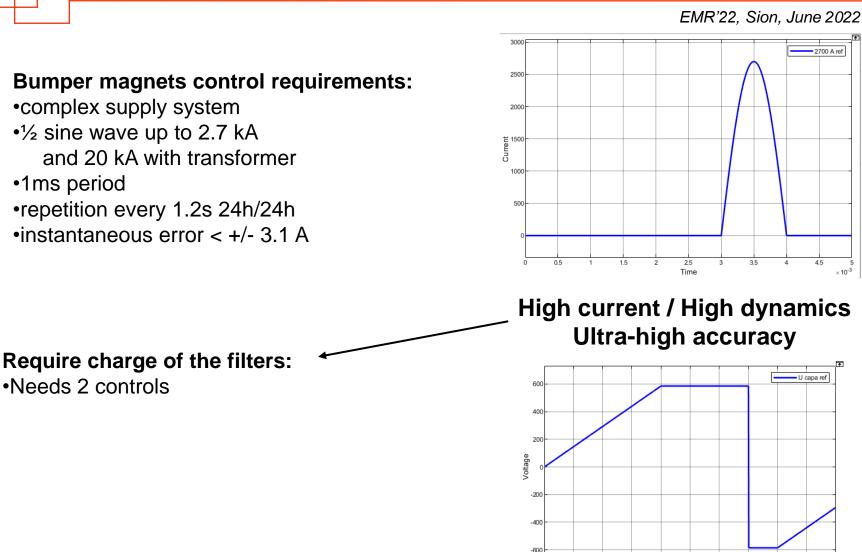




« Context and Objective »



- Objective -



0.5

0

1.5

1

2.5

Time

2

3.5

4

4.5

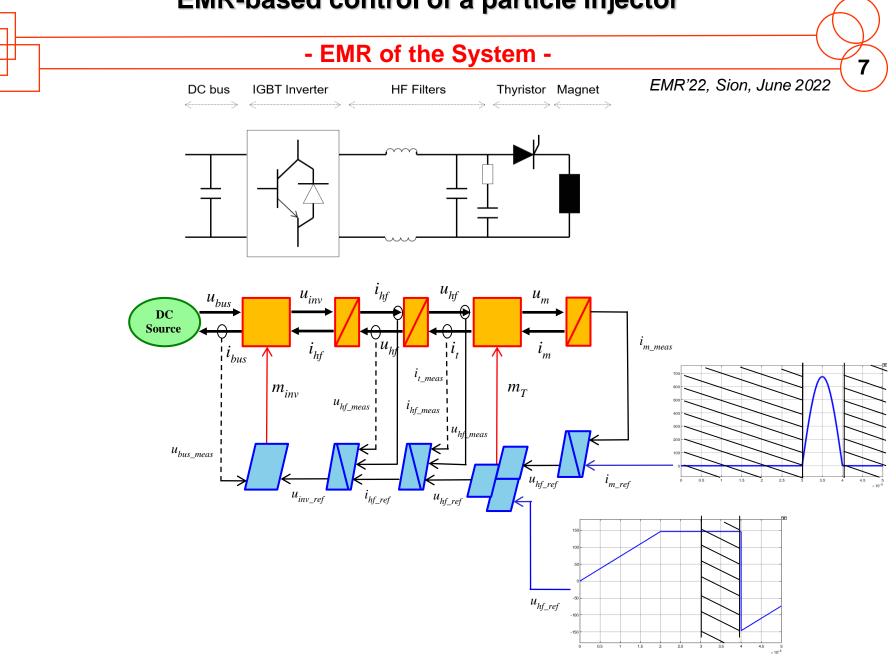
×10⁻³

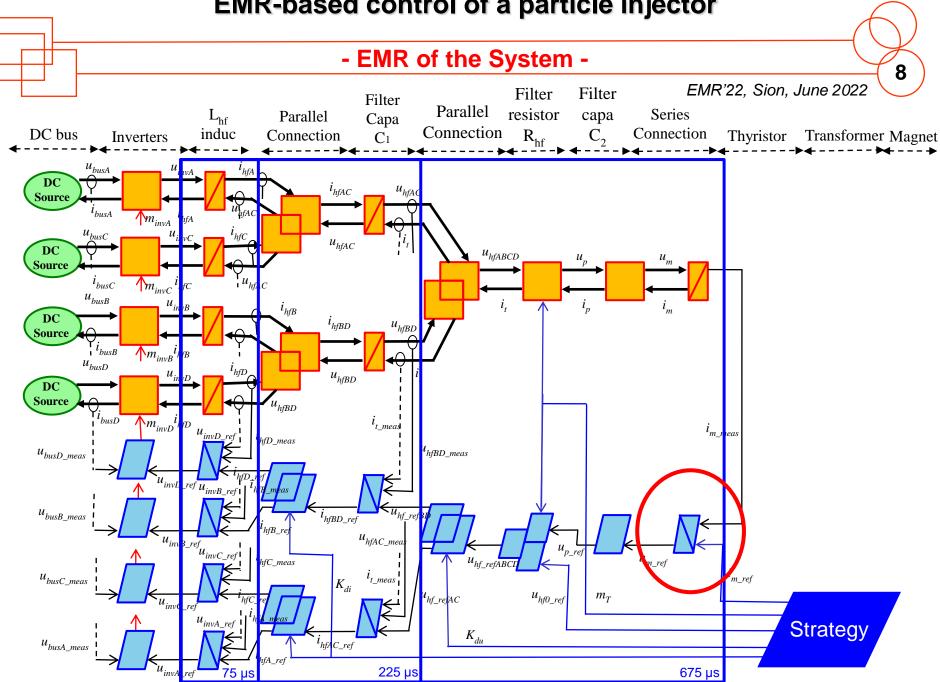
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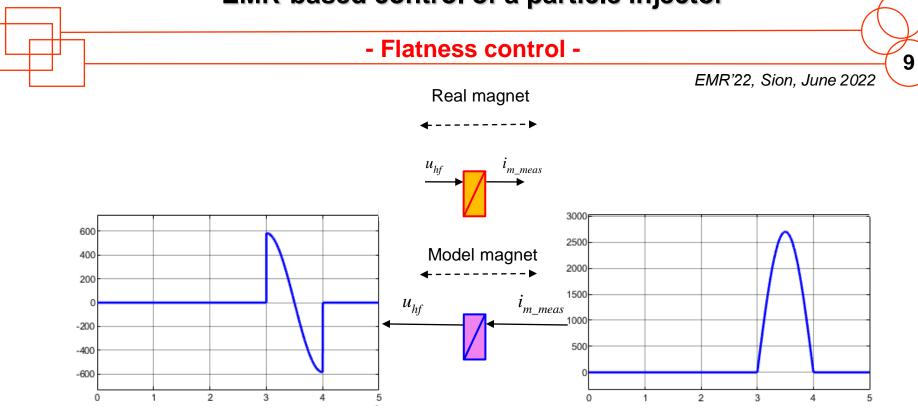
5



« EMR and MCS of the System »

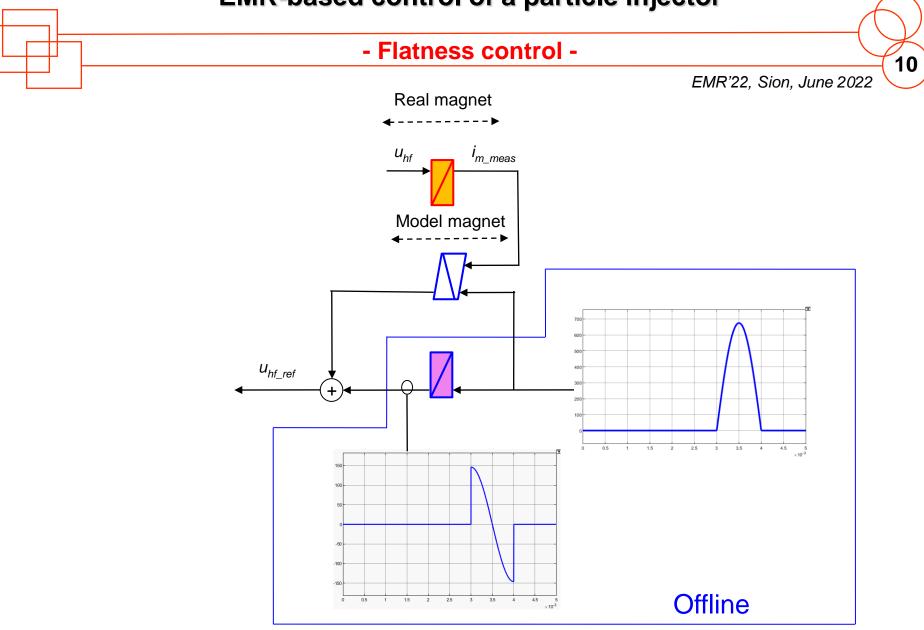


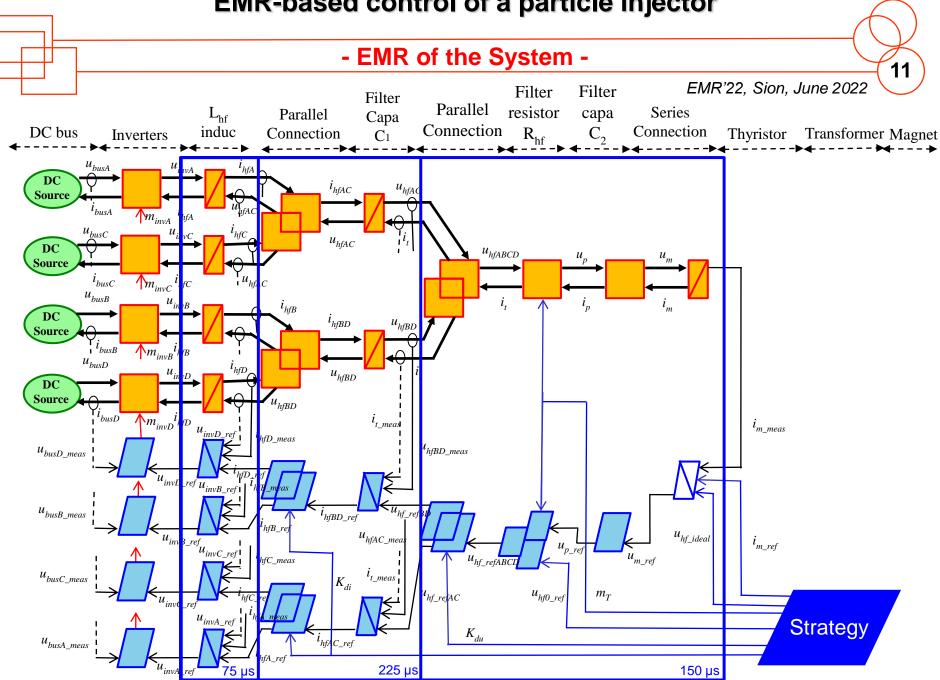




True if we know the reference beforehand

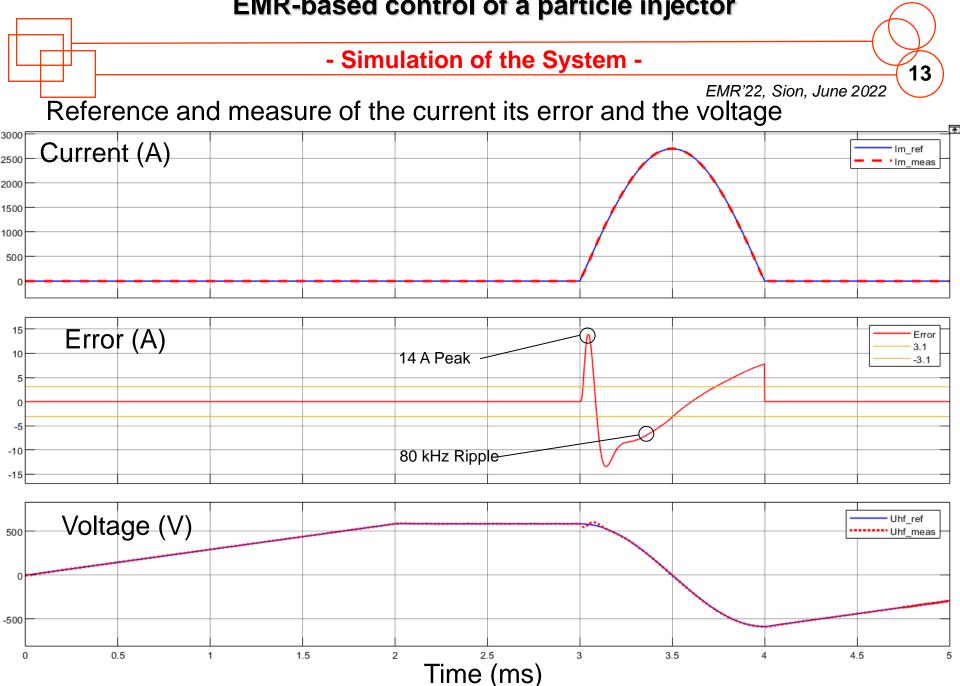
$$\mathbf{u}_{\mathsf{hf_ideal}}$$
: $L_m \frac{d}{dt} i_{m-ref} + R_m i_{m-ref}$

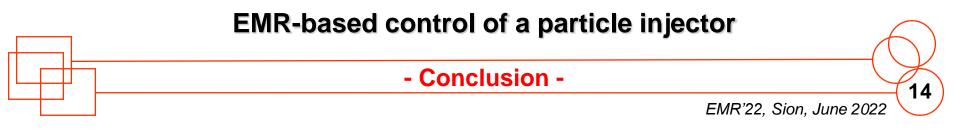






« Simulation of the System »





EMR organize well the system

Allow the implementation of different strategies

Improving discrete response time should be done

In the process of comparing with state feedback control