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June 2022

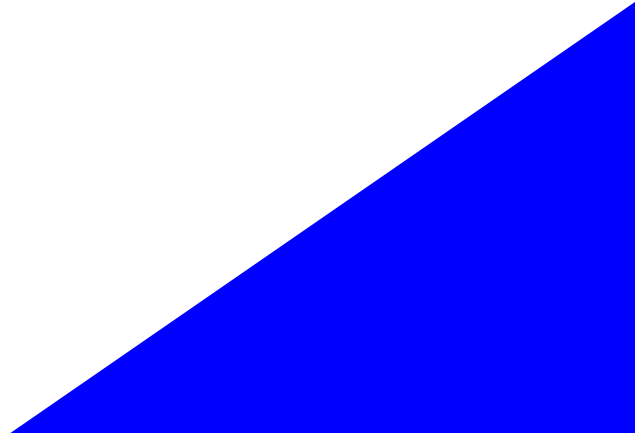


EMR'22 Summer School
“Energetic Macroscopic Representation”

« EMR-based simulation of electric-gas ship »

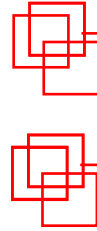
Fabian AMOROS, Walter LHOMME, Jean-Frédéric CHARPENTIER, Jean-Yves BILLARD, Benoit NOTTELLET

University of Lille, Naval Academy Research Institute, Segula Technologies, France





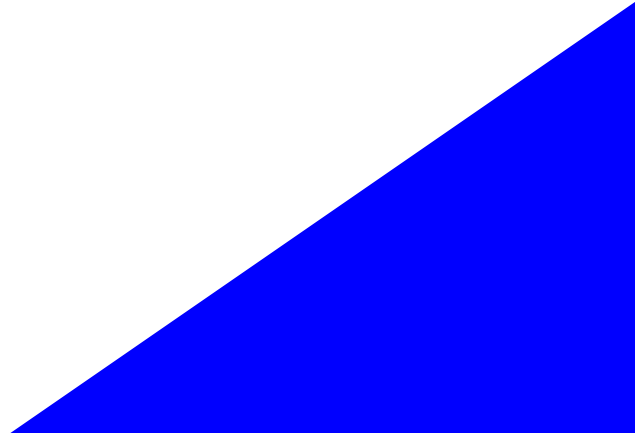
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« INTRODUCTION »



Project : Retrofit a 50 years old Diesel Ship: The Sydney



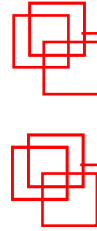
Coalis

- Objectives
 - Show the feasibility of the hybrid retrofit process
 - Gas technology demonstrator
- The Simulator will be used to design the propulsion

- 1 Modelling**
- 2 EMR of the System**
- 3 Simulation Results**
- 4 Conclusion**



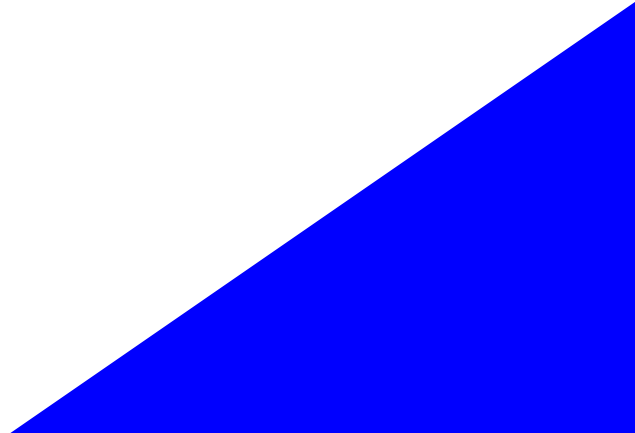
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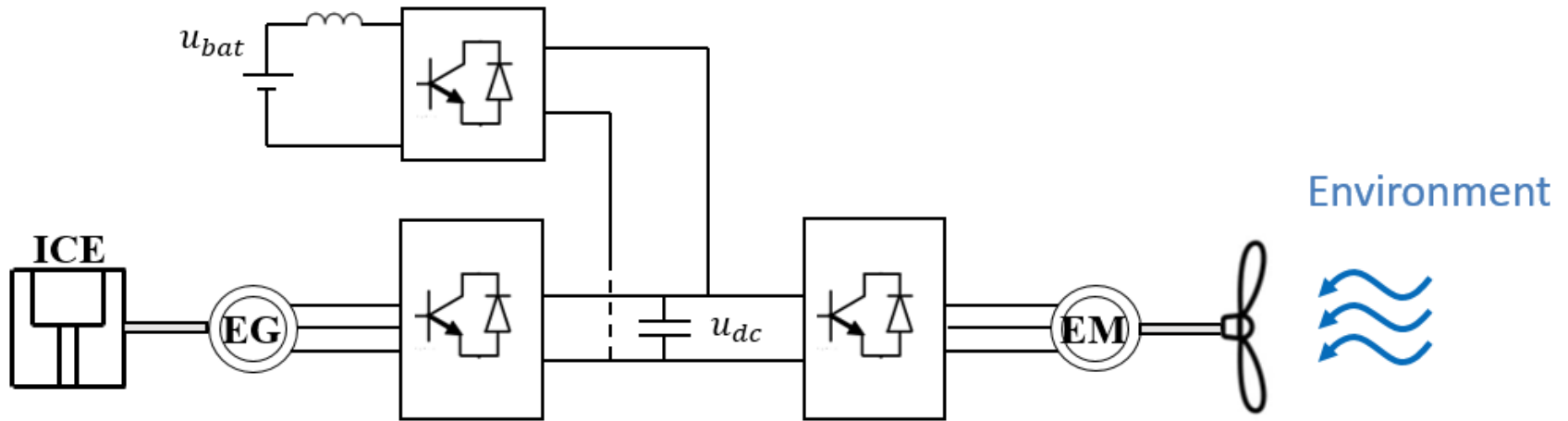


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« MODELLING »





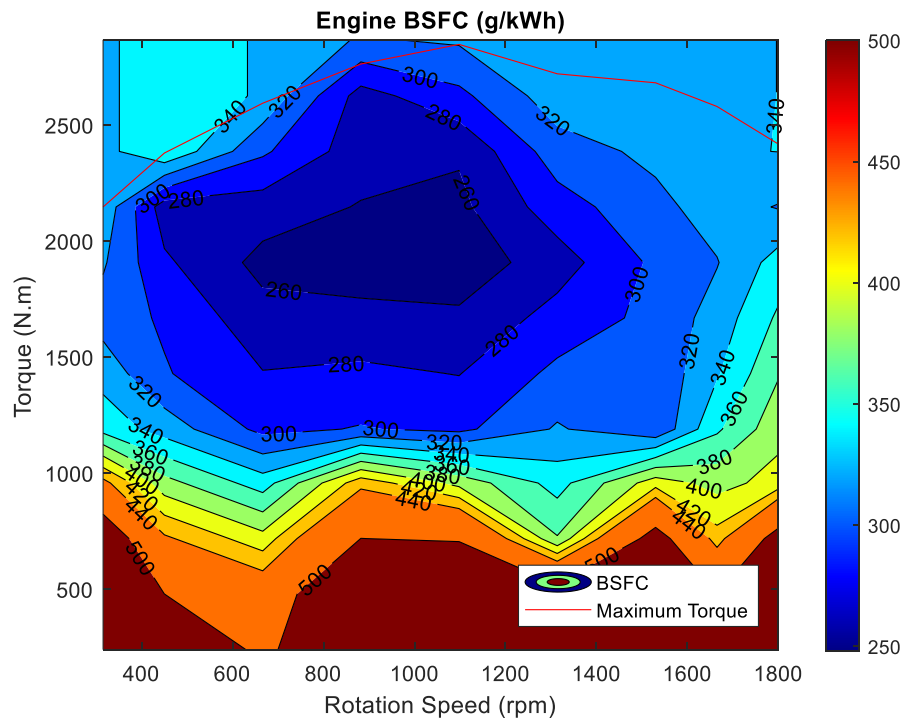
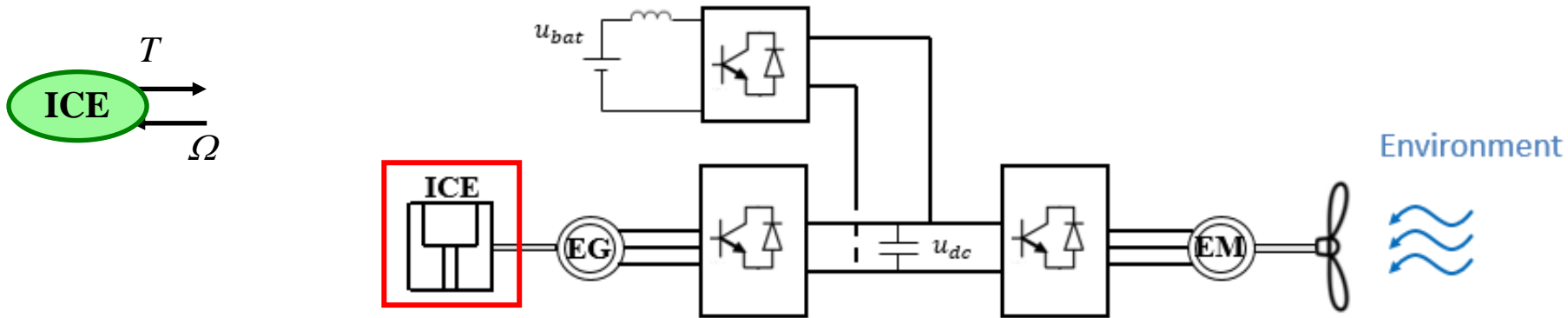
Architecture of the Hybrid vessels

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- Modelling -

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Internal Combustion Engine

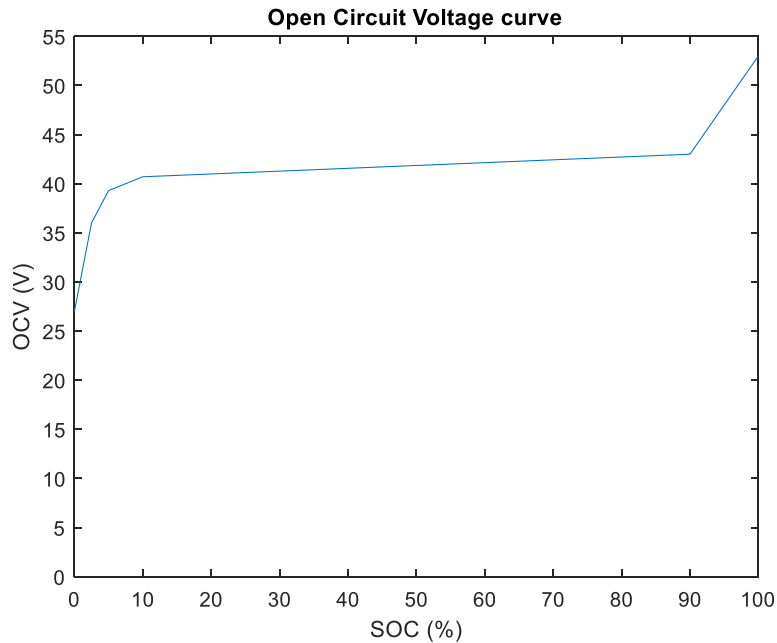
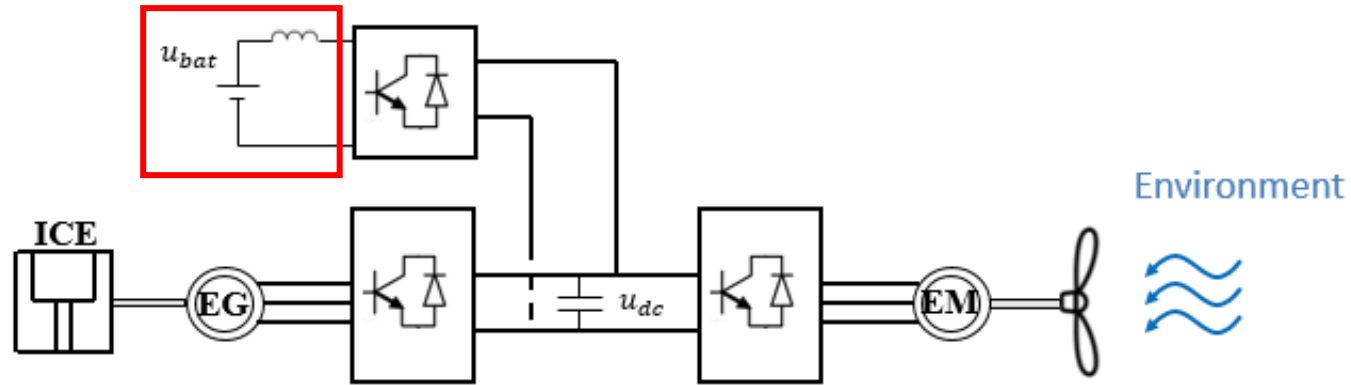
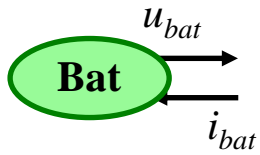
- Brake-Specific Fuel Consumption

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- Modelling -

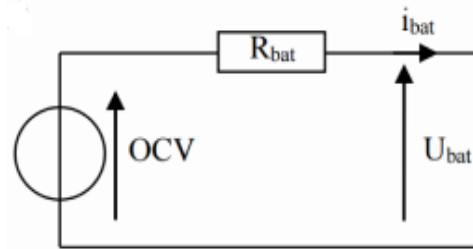
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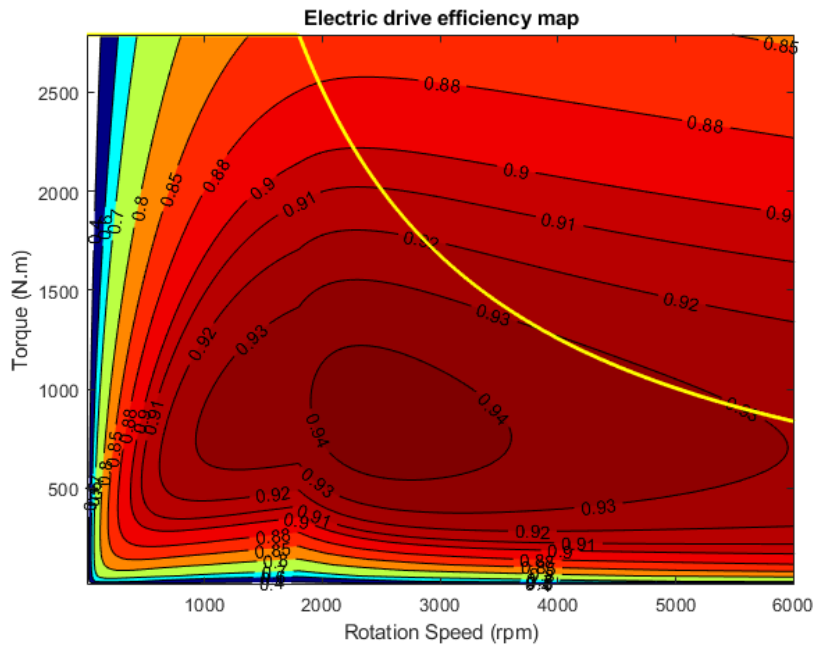
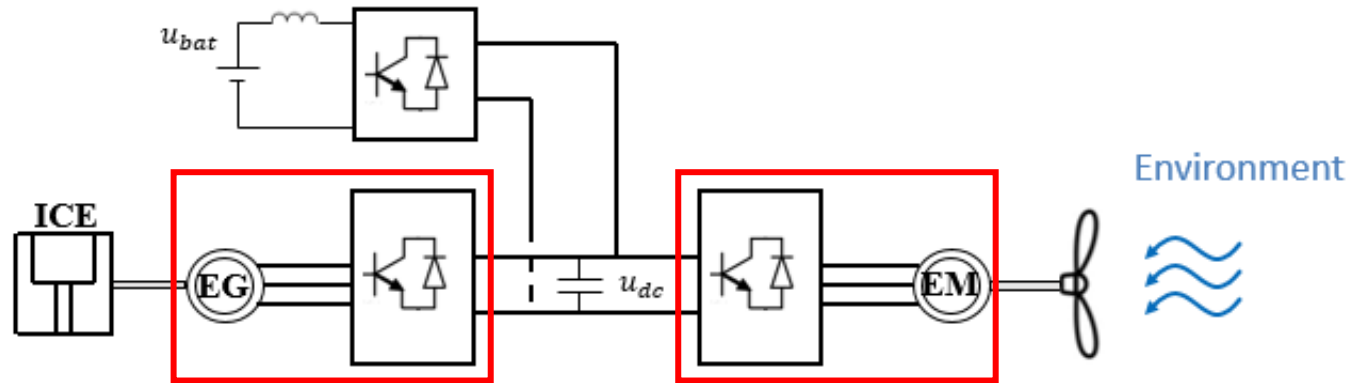
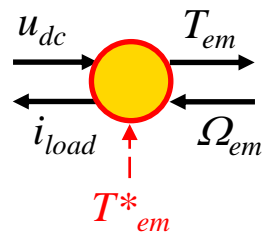
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Battery

- 0 level model





Electric machine + inverter

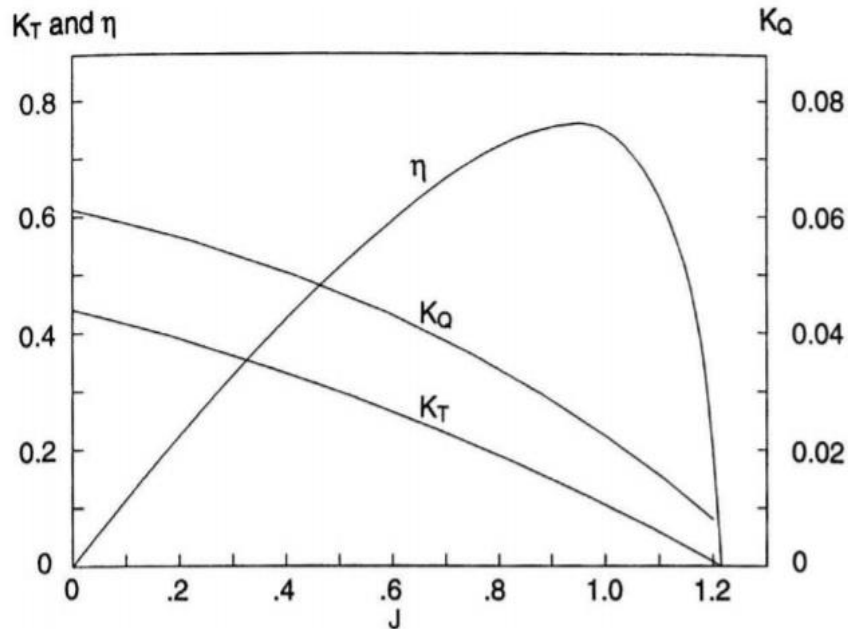
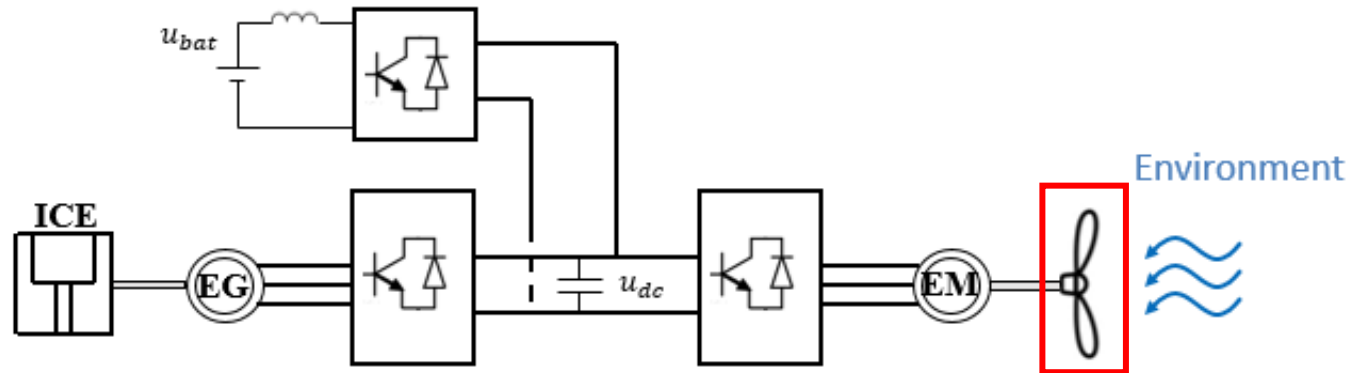
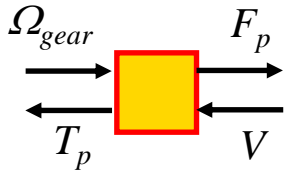
- Efficiency Map from
 - Experimental data
 - Model-based efficiency map

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- Modelling -

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Propeller Empirical model

- $J = \frac{V_a}{n \cdot D}$
- K_T
- K_Q
- $\eta = \frac{J}{2 \cdot \pi} \cdot \frac{K_T}{K_Q}$

Advance parameter

Thrust coefficient

Torque coefficient

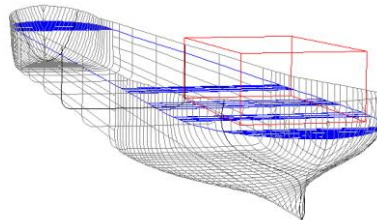
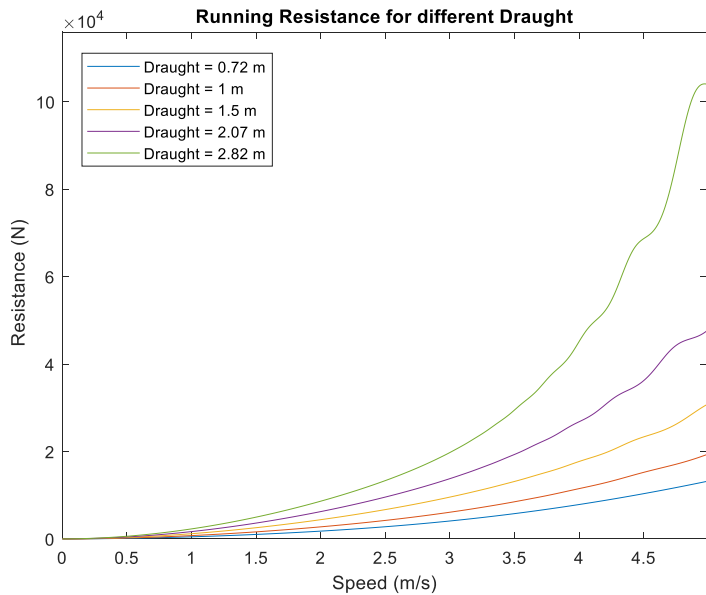
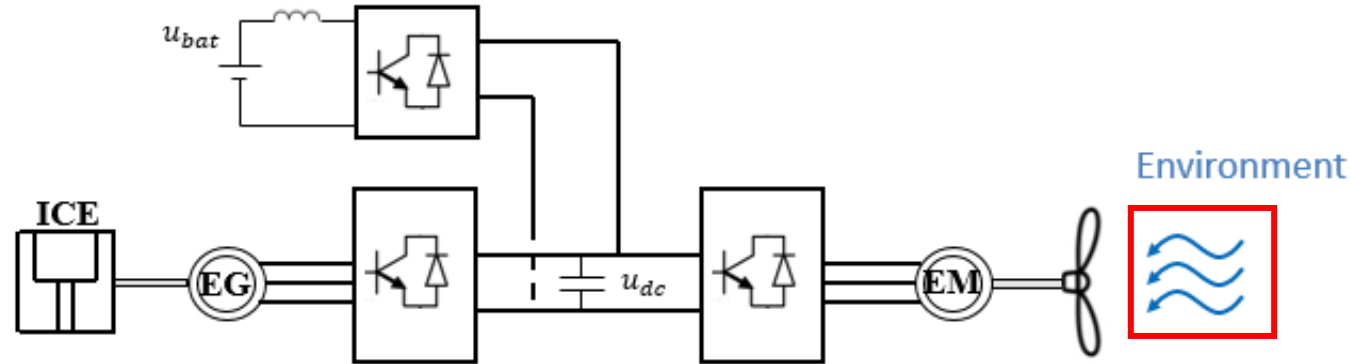
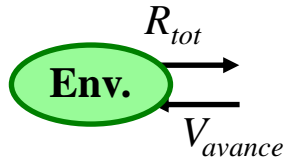
Efficiency

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- Modelling -

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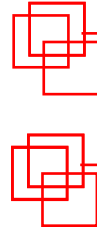


Environment

- Unaccurate empirical model
- Typical 10 – 15 % error



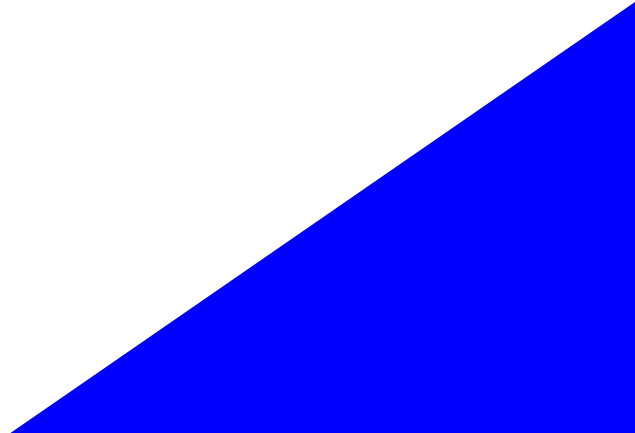
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« EMR OF THE SYSTEM »

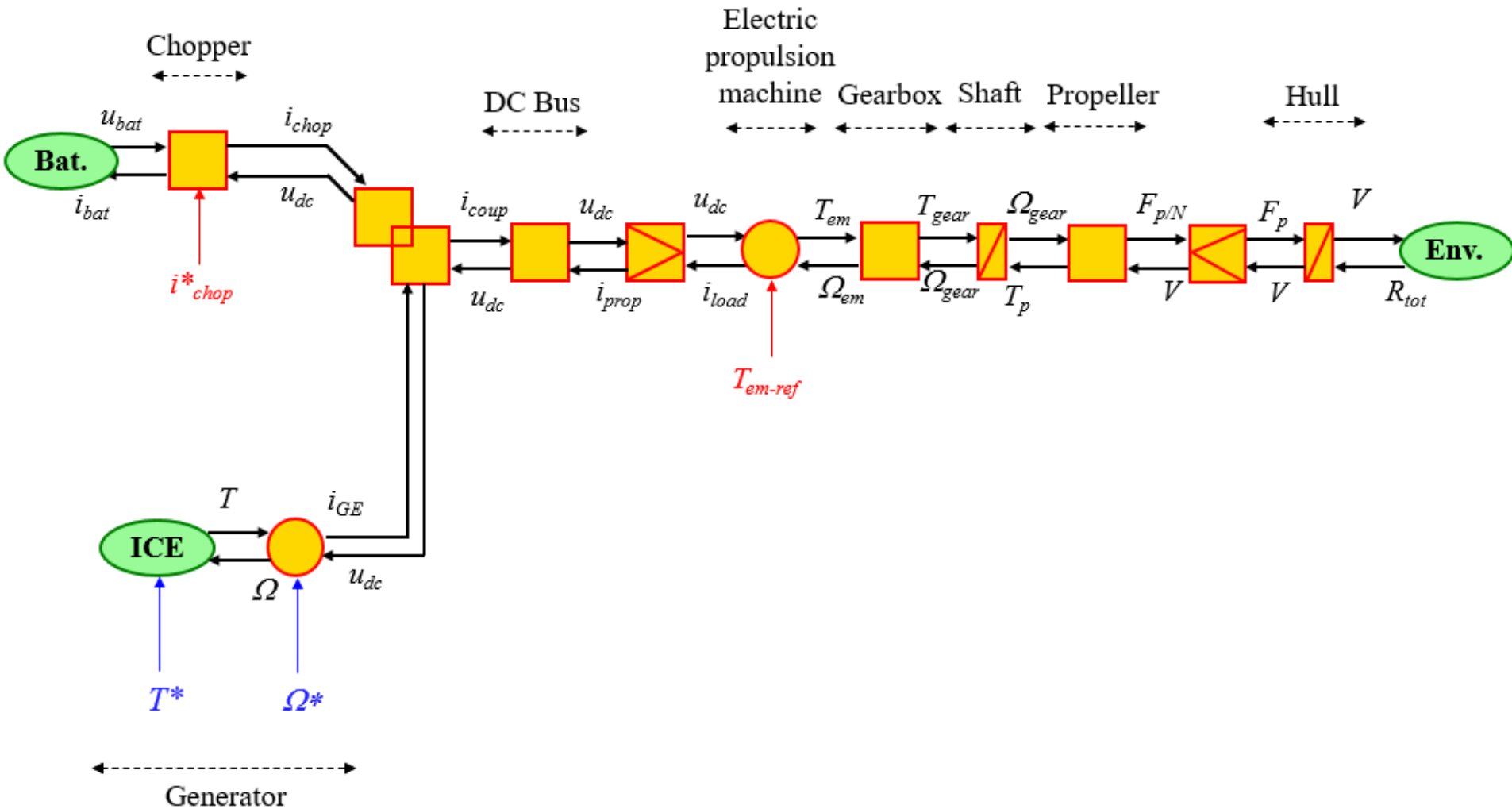


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- EMR of the System -

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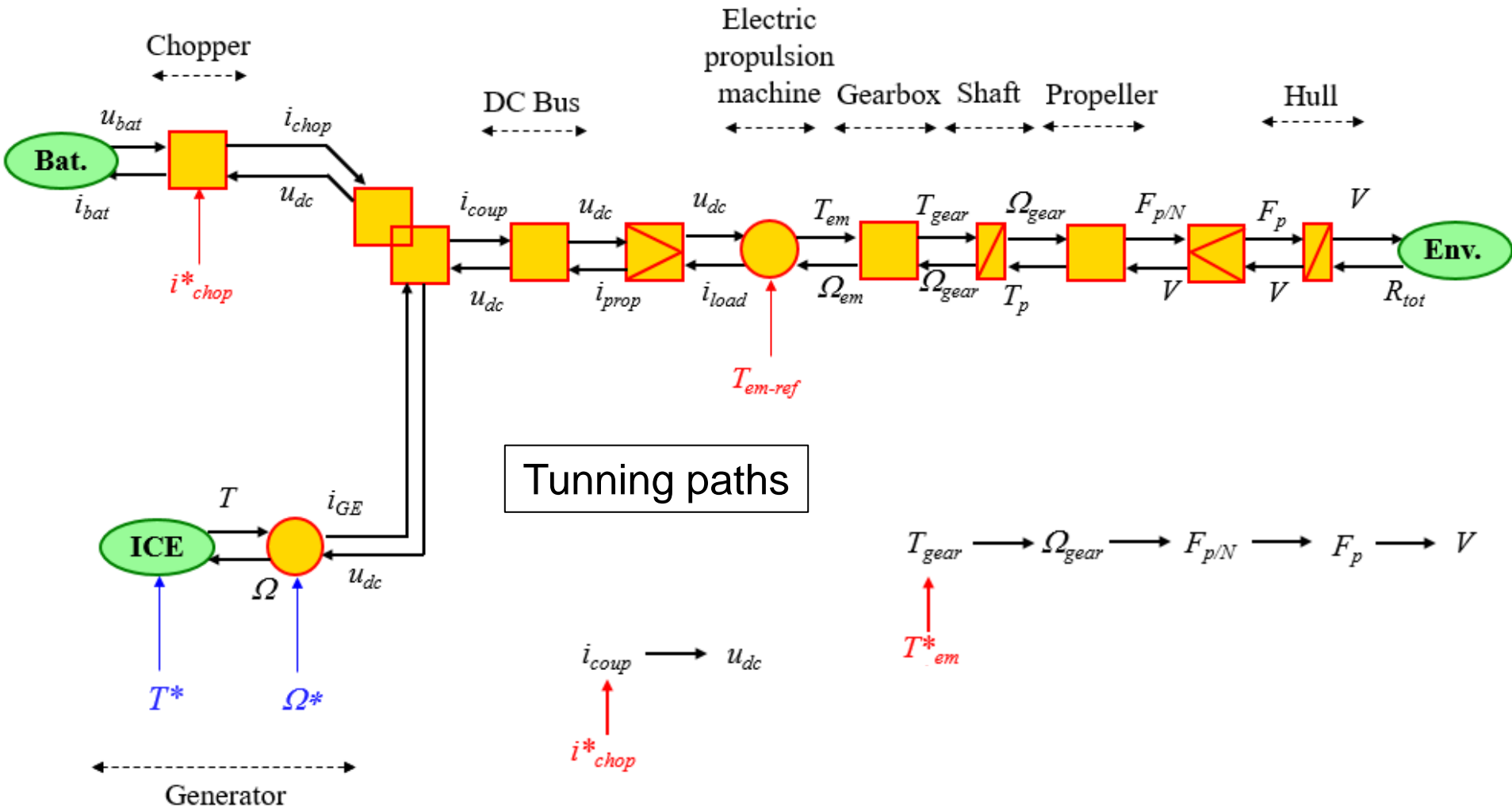


EMR-based simulation of electric-gas ship

- EMR of the System -

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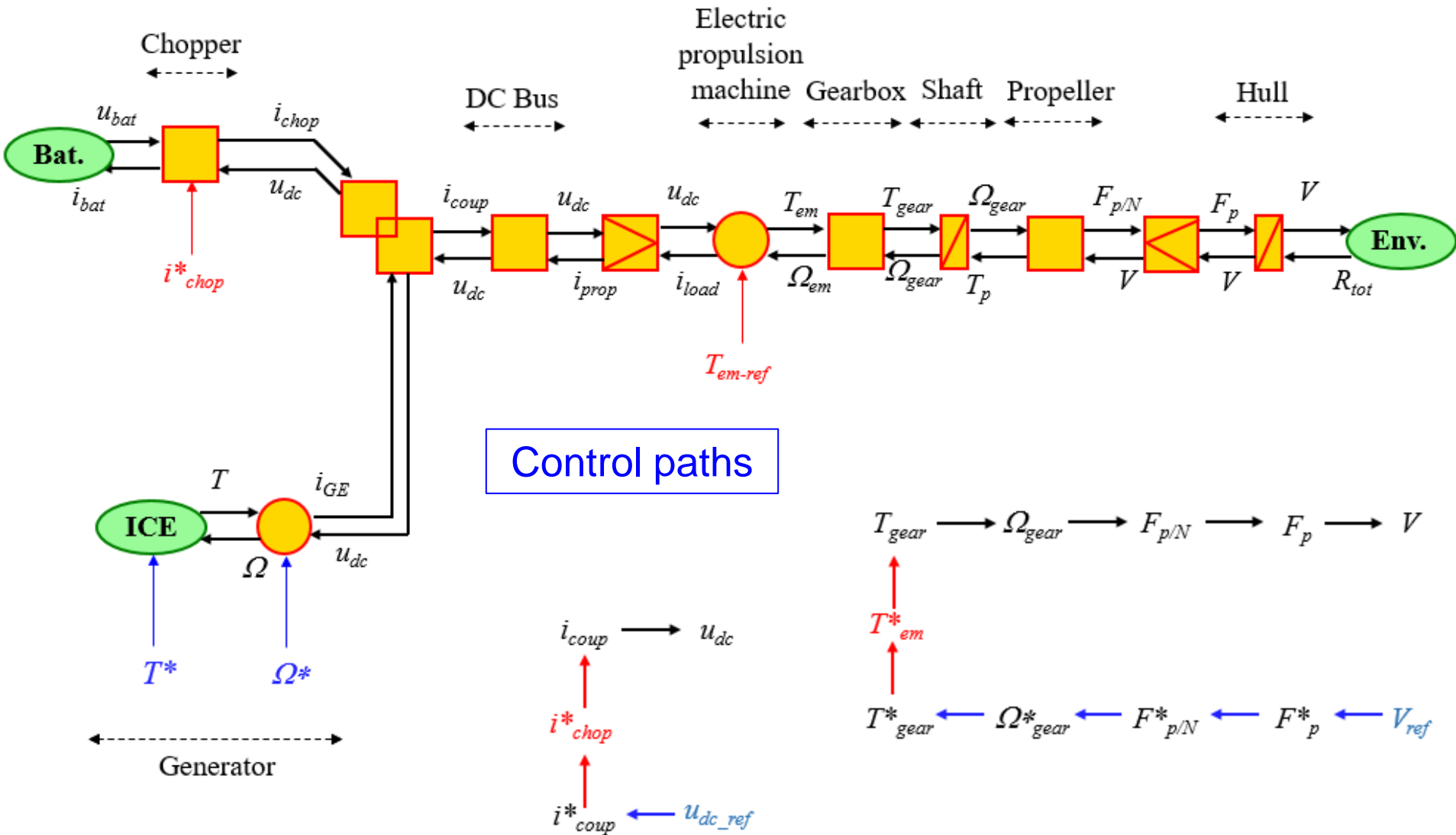


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- EMR of the System -

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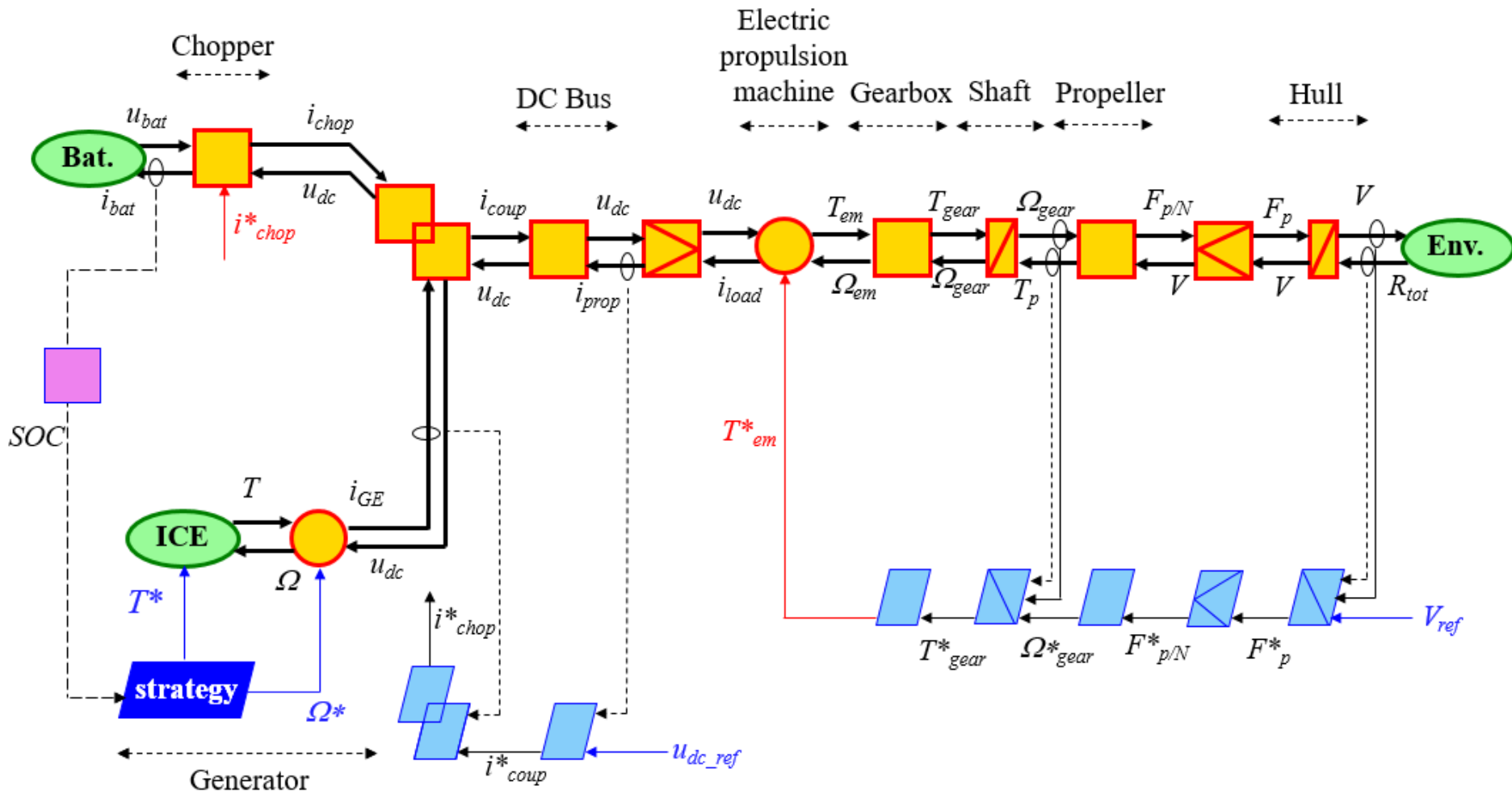


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- EMR of the System -

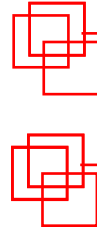
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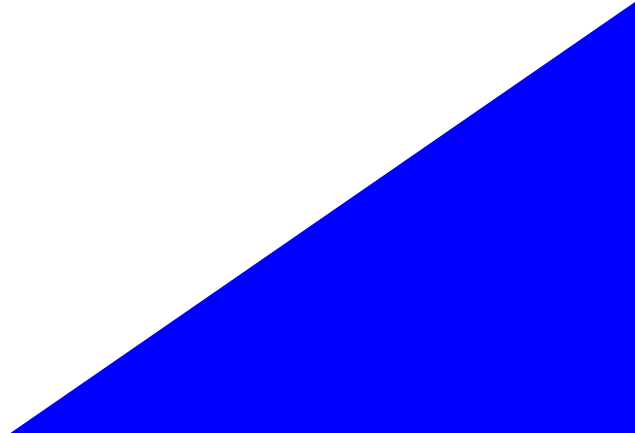
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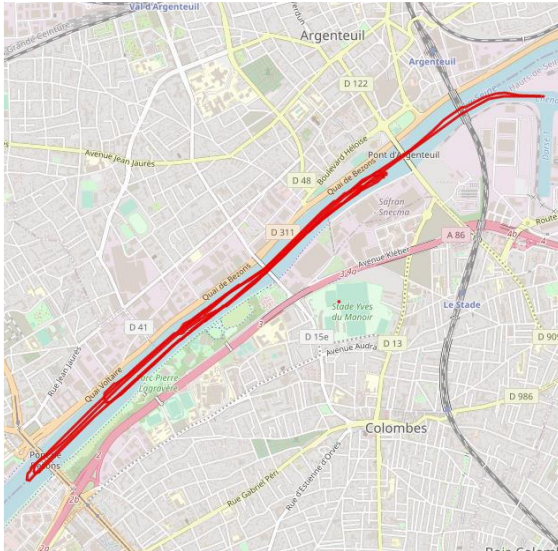


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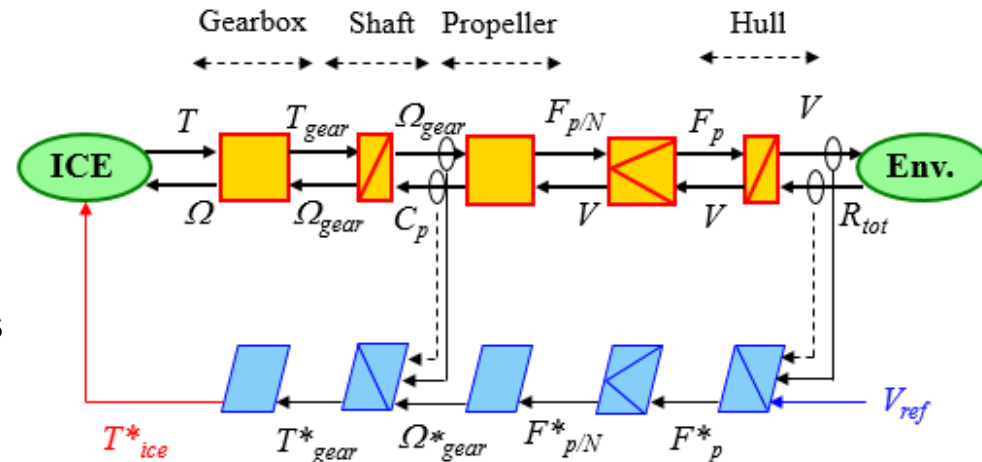


« SIMULATION RESULTS »





- On-board measurement on the Seine River
 - Upstream and downstream navigation at fixed engine rotation speed
 - Rotation Speed ; Power and Torque available



EMR of the current thermic vessels – used for validation

- Simulator Input
 - Design / Parameters of the vessels
 - Advance Speed step

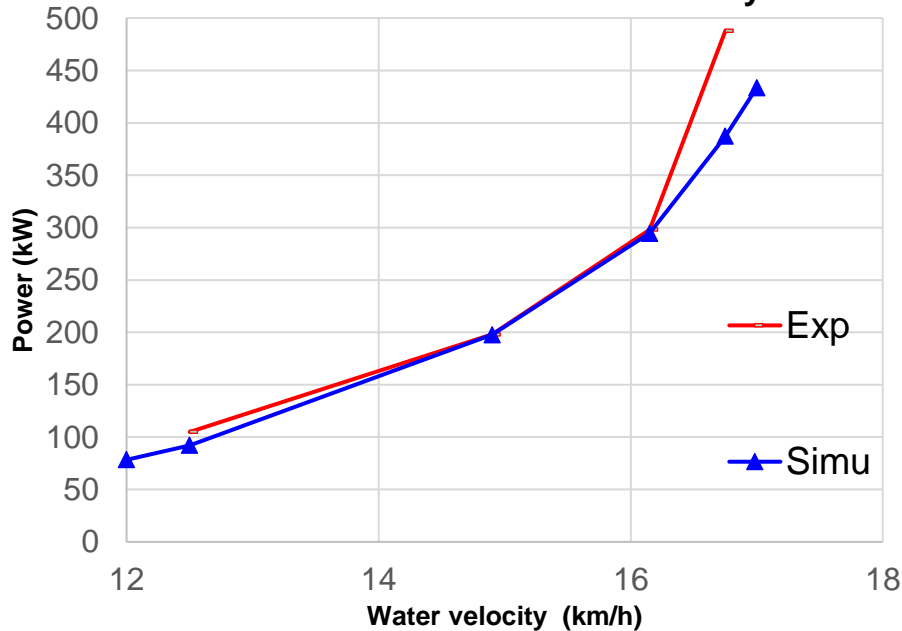
EMR-based simulation of electric-gas ship

- Simulation Results -

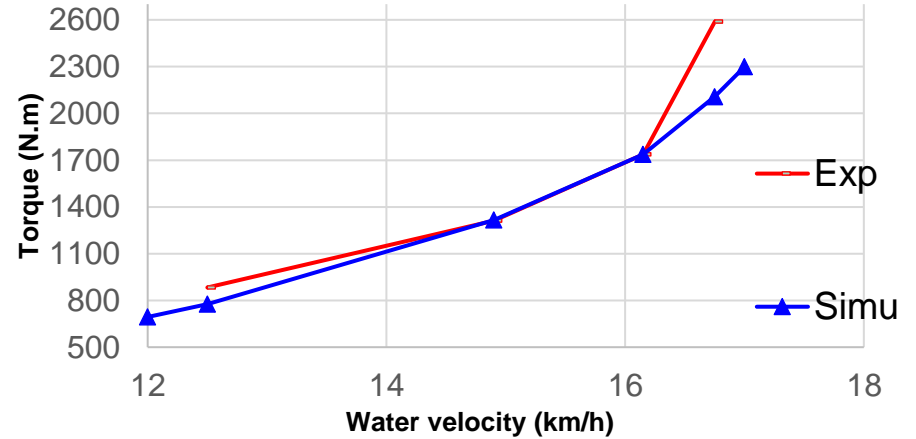
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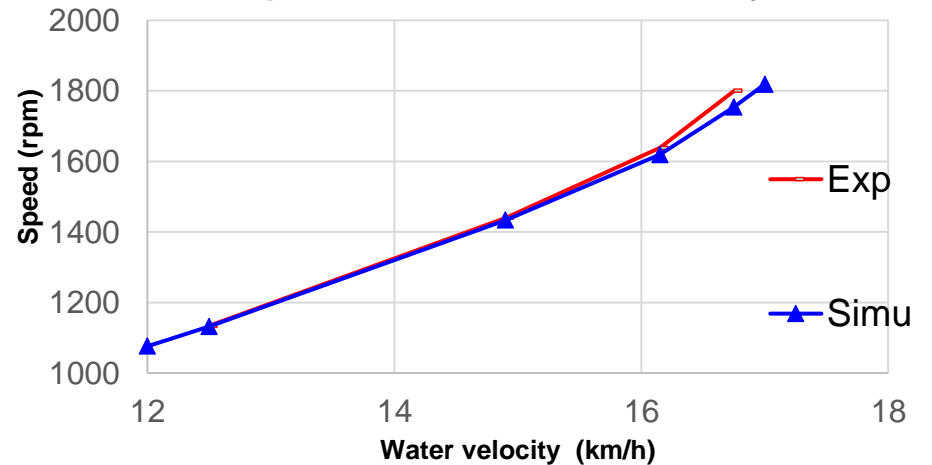
Power for the identified Waterway



Torque for the identified Waterway

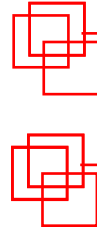


Rpm for the identified Waterway

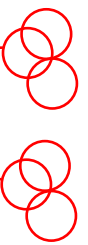




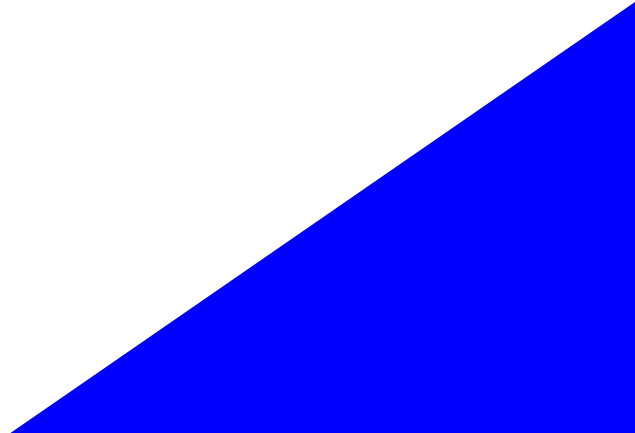
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« CONCLUSION »



- Dynamic validation on progress

- Implementation of a simulation tool using the PANDA approach (EMR)
 - Accurate enough for design purpose

 - Generic
 - For other ship application

 - For other generator technology

 - For other hybrid architecture

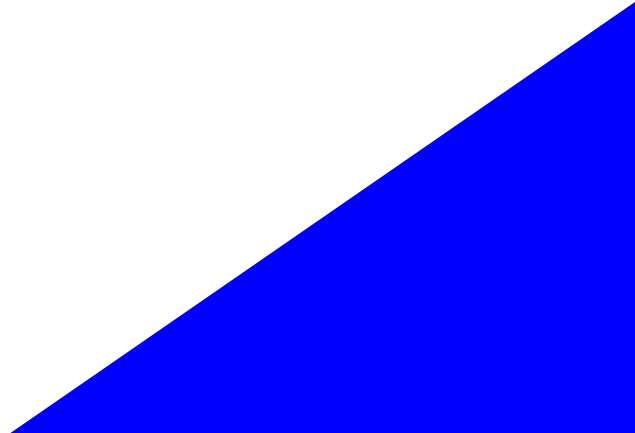


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« **BIOGRAPHIES** »



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- Authors -

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University of Lille, L2EP

PhD student in Electrical Engineering at Arts et Métiers, Paris

Research topics: Hybrid Ship, Naval Propulsion, Control & Design Optimization



Walter LHOMME

University of Lille, France

PhD (2007) and HdR (2020) in Electrical Engineering

Research topics: EMR, HIL simulation, EVs and HEVs,
Energy Storage Subsystem, Traction subsystems,



Jean-frederic.charpentier@ecole-navale.fr

JF Charpentier

Naval Academy Research Institute

Researcher

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marine renewable energy, electric machines and drives





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Jean-yves BILLARD, Ecole navale, Research Institute

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Research topics: Energy efficiency of ships, Naval Propulsion,
Naval hydrodynamics, Dynamic stability



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Benoit NOTTELLET, Segula Technologies

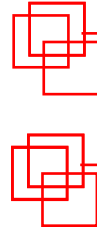
Head of R&I on naval activity

Research topics: Energy efficiency of ships, Naval Propulsion,
Alternative energy for ships, loading optimization





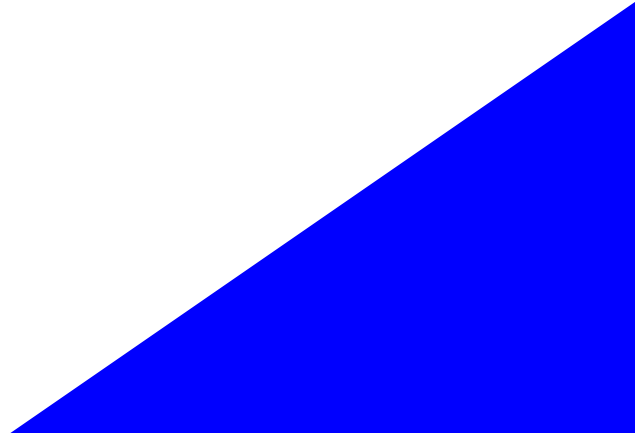
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Thank you for your attention !



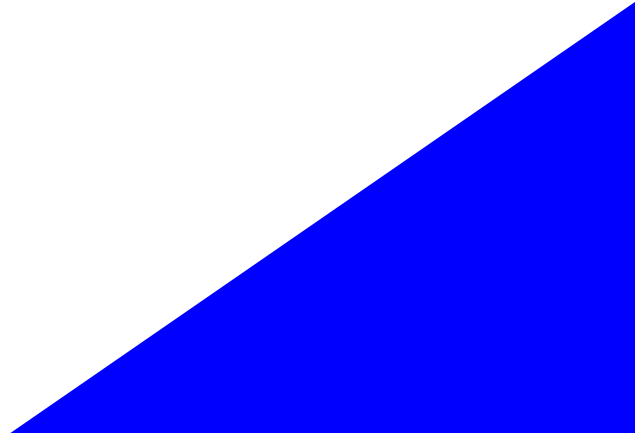


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« Appendix »



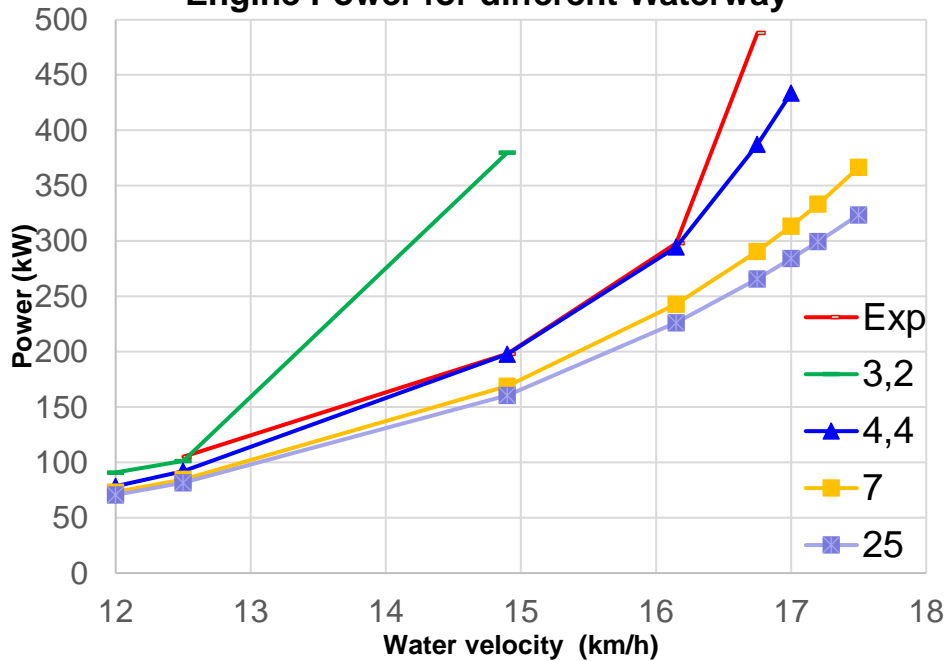
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- Simulation Results for Different Waterway -

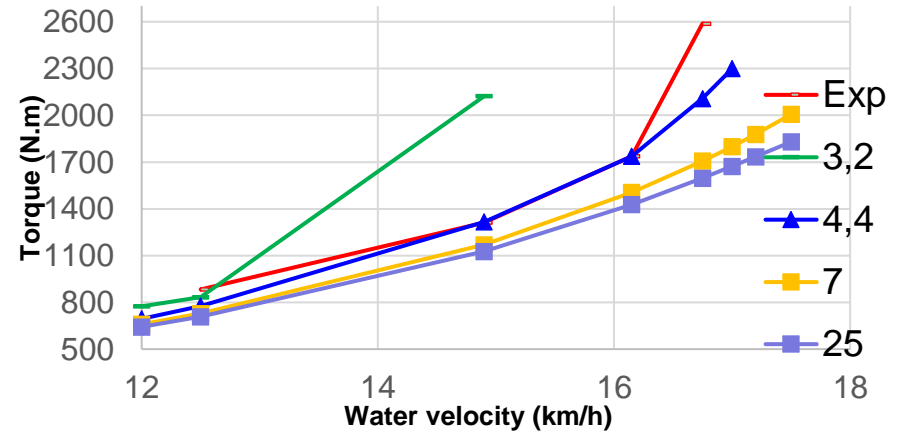
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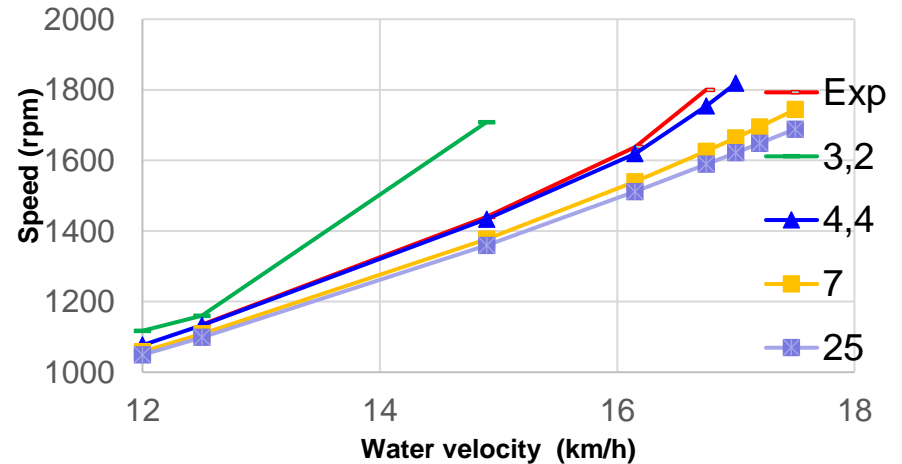
Engine Power for different Waterway

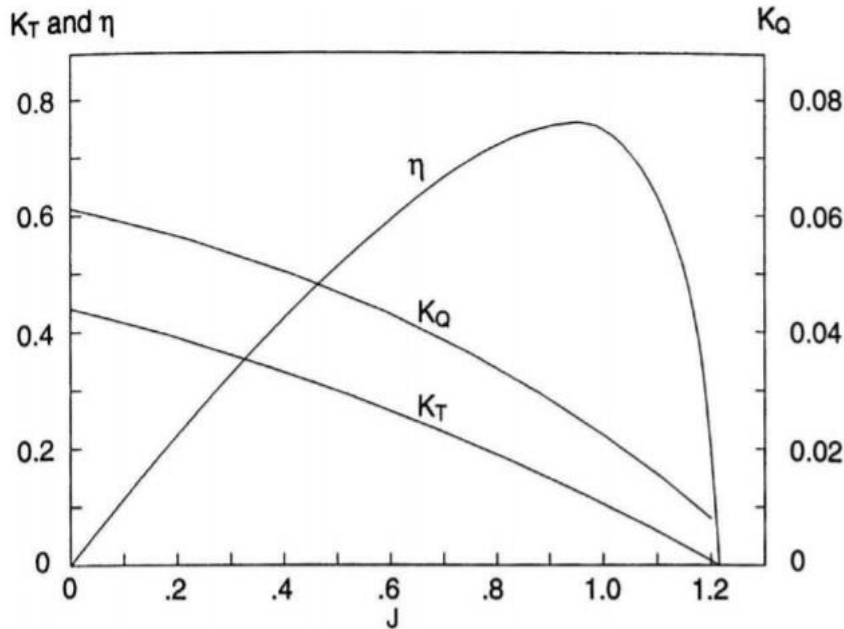


Engine Torque for different Waterway



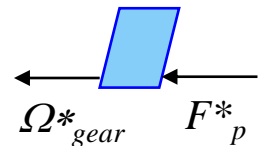
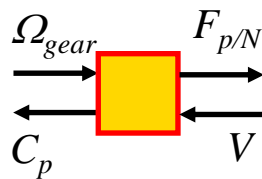
Engine rpm for different Waterway





Propeller Empirical model

- $J = \frac{V_a}{n \cdot D}$ *Advance parameter*
- K_T *Thrust coefficient*
- K_Q *Torque coefficient*
- $\eta = \frac{J}{2 \cdot \pi} \cdot \frac{K_T}{K_Q}$ *Efficiency*



$$F_p = \rho \cdot n^2 \cdot D^4 \cdot K_T \quad (n \text{ rps})$$

$$C_p = \rho \cdot n^2 \cdot D^5 \cdot K_Q$$

$$\eta = \frac{F_p \cdot V}{2 \cdot \pi \cdot n \cdot C_p} = \frac{K_T}{K_Q} \cdot \frac{J}{2 \cdot \pi}$$